

ECE311S: Dynamic Systems and Control

Problem Set 2

Problem 1

You are given a nonlinear system

$$\dot{x}_1 = -x_1 + u$$

$$\dot{x}_2 = -2x_2 + x_3$$

$$\dot{x}_3 = e^{x_1}x_2 + u$$

$$y = x_1 + x_2.$$

- (i) Setting $u = 1$, find the equilibrium point of the system.
- (ii) Find a linearized model of the system about the equilibrium point you found in part (i).

Main Properties of the Laplace Transform

Memorize this table of Laplace transform pairs

$f(t)$	$F(s)$
$\delta(t)$	1
$\mathbf{1}(t)$	$1/s$
$t\mathbf{1}(t)$	$1/s^2$
$t^k\mathbf{1}(t)$ (k integer)	$k!/s^{k+1}$
$e^{at}\mathbf{1}(t)$	$\frac{1}{s-a}$
$t^k e^{at}\mathbf{1}(t)$	$\frac{k!}{(s-a)^{k+1}}$
$\sin(at)\mathbf{1}(t)$	$\frac{a}{s^2+a^2}$
$\cos(at)\mathbf{1}(t)$	$\frac{s}{s^2+a^2}$

where $\mathbf{1}(t)$ denotes the unit step, i.e.

$$\mathbf{1}(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$

The following is a list of the main properties of Laplace transforms. Using these properties you'll be able to solve Problems 1 and 2 without computing any integral. Throughout the following we denote $F(s) := \mathcal{L}\{f(t)\}$, $G(s) := \mathcal{L}\{g(t)\}$.

P1: Linearity $(\forall c_1, c_2 \in \mathfrak{R}) \quad \mathcal{L}\{c_1 f(t) + c_2 g(t)\} = c_1 F(s) + c_2 G(s).$

P2: Differentiation $\mathcal{L}\left\{\frac{d}{dt}f(t)\right\} = sF(s) - f(0^-).$

P3: Integration $\mathcal{L}\left\{\int_0^t f(\tau)d\tau\right\} = \frac{1}{s}F(s).$

P4: Convolution $\mathcal{L}\{f(t) \star g(t)\} = F(s)G(s).$

P5: Time shift Let $T > 0$. Then, $\mathcal{L}\{f(t - T)\mathbf{1}(t - T)\} = e^{-Ts}F(s).$

P6: Shift in s $\mathcal{L}\{e^{at}f(t)\} = F(s - a).$

P7: Multiplication by t $\mathcal{L}\{tf(t)\} = -\frac{dF(s)}{ds}.$

Problem 2

Find the Laplace transform of each of the following time-signals.

1. $f(t) = 3t^2 e^{-t} \cdot \mathbf{1}(t)$
2. $f(t) = \sin t \cos t \cdot \mathbf{1}(t)$
3. $f(t) = \sin(t - 3) \cdot \mathbf{1}(t)$
4. $f(t) = \sin(t - 3) \cdot \mathbf{1}(t - 3)$
5. $f(t) = t \sin(t - 3)\mathbf{1}(t)$
6. $f(t) = (t - 3)e^{t-3}\mathbf{1}(t)$
7. $f(t) = (t - 3)e^{t-3}\mathbf{1}(t - 3)$
8. $f(t) = te^{-at} + 2t \cos t$
9. $f(t) = t^2 + e^{-at} \sin bt$

Problem 3

Find the inverse Laplace transform of each of the following functions.

$$1. \quad F(s) = \frac{s^2 + s + 1}{(s + 1)(s + 2)(s + 3)} \quad (1)$$

$$2. \quad F(s) = \left(\frac{s^2 + s + 1}{(s + 1)(s + 2)(s + 3)} \right) e^{-s} \quad (2)$$

$$3. \quad F(s) = \frac{e^{-2s}}{s - 3} \quad (3)$$

$$4. \quad F(s) = \frac{e^{1-s}}{s} \quad (4)$$

$$5. \quad F(s) = \frac{1}{s^6} \quad (5)$$

$$6. \quad F(s) = \frac{10}{s(s + 1)(s + 10)} \quad (6)$$

$$7. \quad F(s) = \frac{1}{s(s + 2)^2} \quad (7)$$

$$8. \quad F(s) = \frac{2(s + 2)}{(s + 1)(s^2 + 4)} \quad (8)$$

Problem 4

Given $F(s) = \frac{2-s}{(s-1)(s+2)}$, find $\lim_{t \rightarrow +\infty} f(t)$.

Problem 5

Find the solution $y(t)$ to each of the following differential equations

$$1. \quad \ddot{y} + 2\dot{y} + 5y = \exp(-t) \mathbf{1}(t) \quad y(0) = \dot{y}(0) = 0$$

$$2. \quad \ddot{y} - y = \mathbf{1}(t) \quad y(0) = 1, \dot{y}(0) = 1$$

$$3. \quad y^{(4)} + 4y^{(3)} + 8y^{(2)} + 8y^{(1)} + 4y = 3\dot{u} + 4u \quad y(0) = \dot{y}(0) = \dots = y^{(3)}(0) = 0$$

$$u = \mathbf{1}(t)$$

$$4. \quad \ddot{y} + \dot{y} + 3y(t) = 0; \quad y(0) = \alpha, \dot{y}(0) = \beta$$