A Theory of Solvability for Lossless Power Flow Equations

John W. Simpson-Porco



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This talk is based on these papers

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A Theory of Solvability for Lossless Power Flow Equations—Part I: Fixed-Point Power Flow

John W. Simpson-Porco ^(D), Member, IEEE

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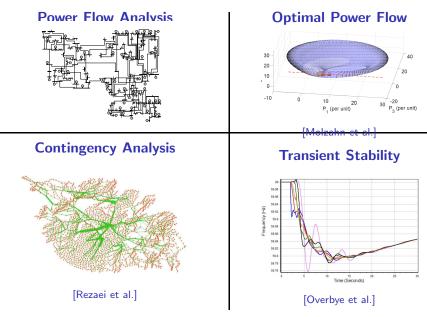
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A Theory of Solvability for Lossless Power Flow Equations—Part II: Conditions for Radial Networks

John W. Simpson-Porco ⁽¹⁰⁾, Member, IEEE

Problems in power system operations



- active power: $P_i = \sum_j V_i V_j B_{ij} \sin(\theta_i \theta_j)$
- reactive power: $Q_i = -\sum_j V_i V_j B_{ij} \cos(\theta_i \theta_j)$



() *n* Loads (**(**) and *m* Generators (**(**) $\mathcal{N} = \mathcal{N}_L \cup \mathcal{N}_G$

O Load Model: PQ bus constant P_i constant Q_i

Generator Model: PV bus consta

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Power Flow Equations $P_i = \sum_j V_i V_j B_{ij} \sin(\theta_i - \theta_j),$ $i \in \mathcal{N}_L \cup \mathcal{N}_G$ $Q_i = -\sum_j V_i V_j B_{ij} \cos(\theta_i - \theta_j),$ $i \in \mathcal{N}_L$

2n + m equations in variables $\theta \in \mathbb{T}^{n+m}$ and $V_L \in \mathbb{R}^n_{>0}$

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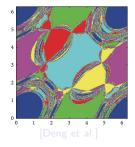
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2n + m equations in variables $\theta \in \mathbb{T}^{n+m}$ and $V_L \in \mathbb{R}^n_{>0}$.

- Because it is interesting to do so
- O Numerical methods
 - understand convergence, divergence, and initialization issues

- State vector: $x = (\theta, V)$
- Newton iteration:

$$x^{k+1} = x^k - J(\theta^k, V^k)^{-1} f(x^k)$$



- Optimal power flow
- Transient stability

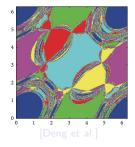
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Output: Numerical methods

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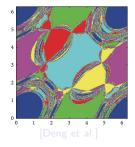


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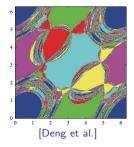


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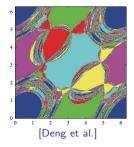


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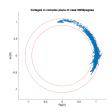
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Intuition on power flow solutions

- 'Normally', exists unique high-voltage soln:
 - voltage magnitude $V_i \simeq 1$
 - phase diff $| heta_i heta_j| \ll 1$



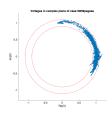
[Josz et al.]

- 2 Lightly loaded systems: many low-voltage solutions
- Heavily loaded systems: Few solutions or infeasible
 - saddle node bifurcations
 - maximum power transfer limit
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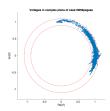
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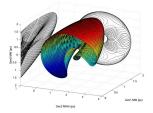
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Given data: network topology, impedances, generation & loads

Q: \exists "stable high-voltage" solution? unique? properties?

Partial answers from **45+ years** of literature:

- Jacobian singularity [Weedy '67]
- Multiple dynamically stable solutions [Korsak '72]
- Existence conditions [Wu & Kumagai '80, '82]
- Active power flow singularity [Araposthatis, Sastry & Varaiya, '81]
- Counting # of solutions [Baillieul and Byrnes '82]
- Properties of quadratic equations [Makarov, Hill & Hiskens '00]
- Optimization approaches [Cañizares '98], [Dvijotham, Low, Chertkov '15], [Molzahn]
- Existence/uniqueness for active power flow [Dörfler, Chertkov & Bullo '12, Delabays, Coletta, and Jacquod '17, JWSP '17, Jafarpour and Bullo '18]
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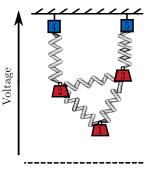
Given data: network topology, impedances, generation & loads
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Partial answers from 45+ years of literature:

Main insight: stiffness vs. loading

- $\textbf{0} \quad \mathsf{Stiff network} + \mathsf{light loading} \Rightarrow \mathsf{feasible}$
- 2 Weak network + heavy loading \Rightarrow infeasible

Q: How to quantify network stiffness vs. loading?



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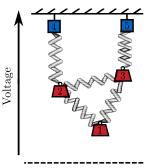
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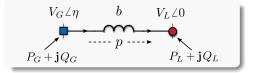
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 $P_L = bV_G V_L \sin(-\eta)$ $P_G = bV_G V_L \sin(\eta)$ $Q_L = bV_L^2 - bV_L V_G \cos(\eta)$



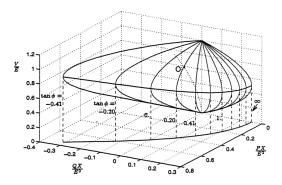
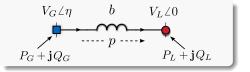


Figure 2.6 Voltage as a function of load active and reactive powers

 $p = bV_G V_L \sin(\eta)$ $Q_L = bV_L^2 - bV_L V_G \cos(\eta)$



O Change Variables

$$v := rac{V_L}{V_G}$$
 $\Gamma := rac{p}{bV_G^2}$ $\Delta := rac{Q_L}{-rac{1}{4}bV_G^2}$

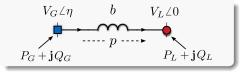
② Square equations, add, and solve quadratic in v^2

$$v_{\pm} = \sqrt{rac{1}{2} \left(1 - rac{\Delta}{2} \pm \sqrt{1 - (4\Gamma^2 + \Delta)}
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O Nec. & Suff. Condition

$$\boxed{4\Gamma^2+\Delta<1}$$

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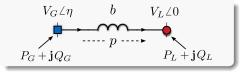
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- **High-voltage** solution $v_+ \in [\frac{1}{2}, 1)$
- 2 **Low-voltage** solution $v_{-} \in [0, \frac{1}{\sqrt{2}})$
- Angle: $sin(\eta_{\mp}) = \Gamma/v_{\pm}$
 - Small-angle solution $\eta_{-} \in [0, \pi/4)$
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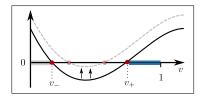
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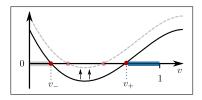


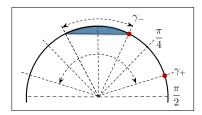
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- Squaring and adding equations does not generalize to networks.
- Is there any hope then?

$$\Gamma = v \sin(\eta)$$
$$\Delta = -4v^2 + 4v \cos(\eta)$$

• Use $\cos(\eta) = \sqrt{1 - \sin^2(\eta)} \implies \Delta = -4v^2 + 4v\sqrt{1 - (\Gamma/v)^2}$

• Rearrange to get *fixed-point equation*

$$v = f(v) := -\frac{1}{4}\frac{\Delta}{v} + \sqrt{1 - \left(\frac{\Gamma}{v}\right)^2}$$

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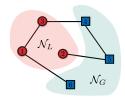
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Network Notation I: Branches Between Bus Types

Power Flow Equations

$$P_i = \sum_j V_i V_j B_{ij} \sin(\theta_i - \theta_j), \qquad i \in \mathcal{N}_L \cup \mathcal{N}_G$$

$$\mathcal{Q}_i = -\sum_j V_i V_j B_{ij} \cos(heta_i - heta_j), \quad i \in \mathcal{N}_L$$



• Bus partitioning $\mathcal{N} = \mathcal{N}_L \cup \mathcal{N}_G$ induces branch partitioning

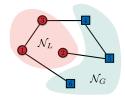
$$\mathcal{E} = \mathcal{E}^{\ell\ell} \cup \mathcal{E}^{g\ell} \cup \mathcal{E}^{gg} , \quad A = \left(\begin{array}{c|c} A_L \\ \hline A_G \end{array} \right) = \left(\begin{array}{c|c} A_L^{\ell\ell} & A_L^{g\ell} & 0 \\ \hline 0 & A_G^{g\ell} & A_G^{gg} \end{array} \right)$$

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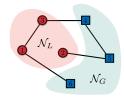
$$\mathcal{E} = \mathcal{E}^{\ell \ell} \cup \mathcal{E}^{g \ell} \cup \mathcal{E}^{g g}, \quad A = \left(\frac{A_L}{A_G}\right) = \left(\frac{A_L^{\ell \ell}}{0} \begin{vmatrix} A_L^{g \ell} & 0 \end{vmatrix} - \frac{A_L^{\ell \ell}}{0} \begin{vmatrix} A_L^{g \ell} & A_G^{g \ell} \end{vmatrix} - \frac{A_L^{g \ell}}{0} \end{vmatrix}$$

Network Notation I: Branches Between Bus Types

Power Flow Equations

$$P_i = \sum_j V_i V_j B_{ij} \sin(\theta_i - \theta_j), \qquad i \in \mathcal{N}_L \cup \mathcal{N}_G$$

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$$\mathcal{E} = \mathcal{E}^{\ell\ell} \cup \mathcal{E}^{g\ell} \cup \mathcal{E}^{gg} , \quad A = \left(\begin{array}{c|c} A_L \\ \hline A_G \end{array} \right) = \left(\begin{array}{c|c} A_L^{\ell\ell} & A_L^{g\ell} & \mathbb{0} \\ \hline \mathbb{0} & A_G^{g\ell} & A_G^{gg} \end{array} \right)$$

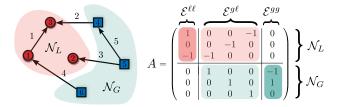
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Power Flow Equations

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- Loads \mathcal{N}_L : V_i free

Partitioned Variables

$$V = \left(\frac{V_L}{V_G}\right), \qquad B = \left(\frac{B_{LL} \mid B_{LG}}{B_{GL} \mid B_{GG}}\right)$$

$$V_{L}^{*} \triangleq \underbrace{-B_{LL}^{-1}B_{LG}}_{Generators \to Loads} \cdot V_{G}$$

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Generators→Loads

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$$v_i \triangleq V_i / V_i^*$$

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• Need to non-dimensionalize power flow equations

• Stiffness matrices quantify grid strength in units of power

O Nodal stiffness matrix

2 Branch stiffness matrix

$$\mathsf{S} \triangleq \frac{1}{4} \left[V_L^* \right] \cdot B_{LL} \cdot \left[V_L^* \right]$$

$$\mathsf{D} \triangleq [V_i^* V_j^* B_{ij}]_{(i,j)\in\mathcal{E}}$$

$$\mathsf{L} \triangleq \mathsf{A}\mathsf{D}\mathsf{A}^\mathsf{T}$$

$$V = \left(\frac{V_L}{V_G}\right), \quad B = \left(\frac{B_{LL} \mid B_{LG}}{B_{GL} \mid B_{GG}}\right), \quad V_L^* = -B_{LL}^{-1} B_{LG} V_G$$

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$$L \triangleq ADA^{T}$$

Fixed-Point Power Flow: Meshed Networks

 (θ, V_L) is a power flow solution iff (v, p_c) solves the FPPF

 $\begin{aligned} \mathbf{v} &= f(\mathbf{v}, p_c) \triangleq \mathbb{1}_n - \frac{1}{4} \mathbf{S}^{-1}[Q_L][\mathbf{v}]^{-1} \mathbb{1}_n \\ &+ \frac{1}{4} \mathbf{S}^{-1}[\mathbf{v}]^{-1} |A|_L \mathbf{D}[h(\mathbf{v})] u(\mathbf{v}, p_c), \end{aligned}$ $\mathbf{D}_c &= C^{\mathsf{T}} \operatorname{arcsin}(\psi(\mathbf{v}, p_c)). \end{aligned}$

where

$$u(v, p_c) \triangleq \mathbb{1} - \sqrt{\mathbb{1} - [\psi]\psi}$$

$$\psi(v, p_c) = [h(v)]^{-1} \left(A^{\mathsf{T}} \mathsf{L}^{\dagger} P + \mathsf{D}^{-1} C \mathsf{p}_c \right) + \mathbf{1} \mathbf{C} \mathsf{P}_c \mathbf{C} \mathsf{P}_$$

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• The model says $v = f(v, p_c)$, and $sin(A^T \theta) = \psi(v, p_c)$.

• By construction, when $P = Q_L = 0$, a solution is

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$$\begin{split} A^{\mathsf{T}}\theta_{\mathrm{approx}} &= A^{\mathsf{T}}L^{\dagger}P\\ \mathbf{v}_{\mathrm{approx}} &\simeq \mathbb{1}_{n} - \frac{1}{4}\mathsf{S}^{-1}Q_{L} + \frac{1}{8}\mathsf{S}^{-1}|A|_{L}\mathsf{D}[A^{\mathsf{T}}\mathsf{L}^{\dagger}P]A^{\mathsf{T}}\mathsf{L}^{\dagger}P\\ P_{\mathsf{c},\mathrm{approx}} &= 0 \end{split}$$

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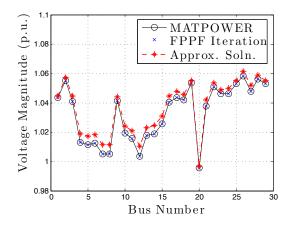
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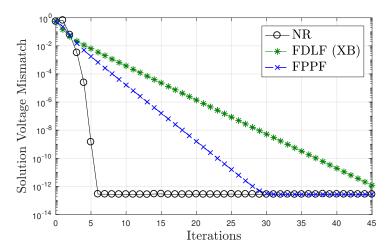
Numerical Results I

$$\delta_{\max} = \| \mathbf{v} - \mathbf{v}_{approx} \|_{\infty}, \quad \delta_{avg} = \frac{1}{n} \| \mathbf{v} - \mathbf{v}_{approx} \|_{1}$$

	Base Load			High Load	
Test Case	FPPF Iters.	$\delta_{\rm max}$	$\delta_{\rm avg}$	FPPF Iters.	$\delta_{\rm max}$
	iters.	(p.u.)	(p.u.)	iters.	(p.u.)
New England 39	4	0.006	0.004	8	0.086
57 bus system	5	0.011	0.003	8	0.118
RTS '96 (3 area)	4	0.003	0.001	8	0.084
118 bus system	3	0.001	0.000	7	0.054
300 bus system	6	0.022	0.004	8	0.059
PEGASE 1,354	5	0.011	0.001	8	0.070
Polish 2,383 wp	4	0.003	0.000	8	0.078
PEGASE 2,869	5	0.015	0.002	8	0.098
PEGASE 9,241	6	0.063	0.003	9	0.133

Numerical Results II – Convergence Rates

• IEEE 300 bus system under heavy loading



Numerical Results III - Sensitivity to Initialization

- perturb voltage magnitude initialization randomly
- IEEE 118 bus system, base case

IC Spread (α)	NR	FDLF	FPPF
0.05	0.98	0.98	1.00
0.10	0.53	0.53	1.00
0.15	0.18	0.18	1.00
0.2	0.03	0.03	1.00
0.3	0.00	0.00	1.00
0.5	0.00	0.00	1.00
0.7	0.00	0.00	0.99
0.9	0.00	0.00	0.99

• extreme insensitivity to initialization (contraction)



 (θ, V_L) is a power flow solution iff v is a fixed point of

$$f(v) \triangleq \mathbb{1}_n - \frac{1}{4} S^{-1}[Q_L][v]^{-1} \mathbb{1}_n + \frac{1}{4} S^{-1}[v]^{-1} |A|_L D[h(v)] u(v),$$

where
$$u(v) \triangleq \mathbb{1} - \sqrt{\mathbb{1} - [\psi] \psi}$$
$$\psi(v) = [h(v)]^{-1} D^{-1} p$$
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$$u(\mathbf{v}) \triangleq \mathbb{1} - \sqrt{\mathbb{1} - [\psi]\psi}$$

$$\psi(\mathbf{v}) = [h(\mathbf{v})]^{-1}\mathsf{D}^{-1}p$$

$$p = (A^{\mathsf{T}}A)^{-1}A^{\mathsf{T}}P$$

Fixed-Point Power Flow: Radial Networks

 (θ, V_L) is a power flow solution iff v is a fixed point of

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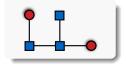
with the phase angles $A^{\mathsf{T}}\theta = \operatorname{arcsin}(\psi)$.

On what invariant set is *f* a **contraction**?

Solvability Results for Different Acyclic Topologies

Solvability Results for Different Acyclic Topologies

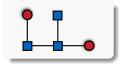
PQ buses have one PV bus neighbor



 $\begin{array}{l} {\sf Sufficient} + {\sf Necessary} \\ {\sf Existence} + {\sf Uniqueness} \end{array}$

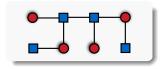
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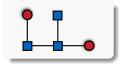
PQ buses have many PV bus neighbors



Sufficient + Tight Existence + Uniqueness

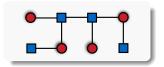
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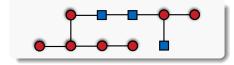
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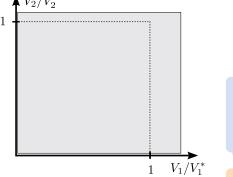
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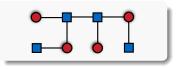
General interconnections



Sufficient Existence



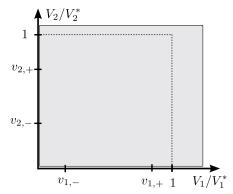


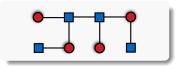


 $\max_{i\in\mathcal{N}_L} \ \Delta_i + 4\Gamma_i^2 < 1$ $\max_{(i,j)\in\mathcal{E}^{gg}}\Gamma_{ij}<1\,,$

$$\mathsf{v}_{i,\pm} \triangleq \sqrt{rac{1}{2} \left(1 - rac{\Delta_i}{2} \pm \sqrt{1 - (\Delta_i + 4\Gamma_i^2)}
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$$v_{i,+}^2 - v_{i,-}^2 = \sqrt{1 - (\Delta_i + 4\Gamma_i^2)}.$$

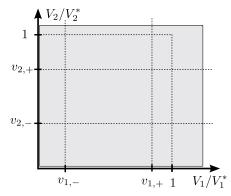


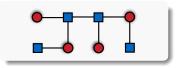


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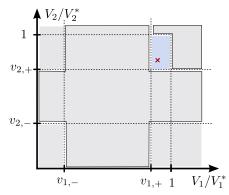
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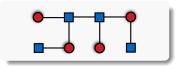




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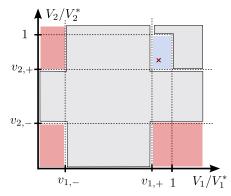
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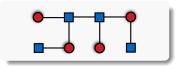




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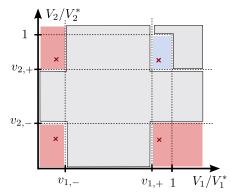
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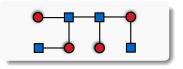




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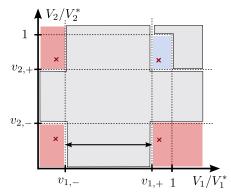
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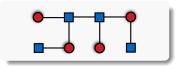




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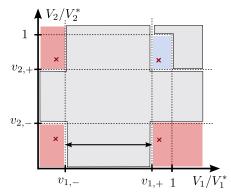


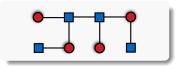


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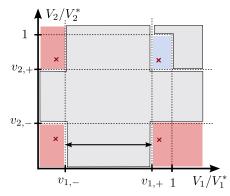
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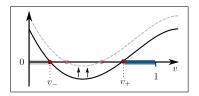


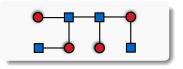


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What About Networks with Losses?

IEEE TRANSACTIONS ON POWER SYSTEMS, VOL. 33, NO. 3, MAY 2018

Lossy DC Power Flow

John W. Simpson-Porco⁽⁰⁾, Member, IEEE

Focus just on active power balance (minus slack bus)

$$P_i = \sum_j V_i V_j B_{ij} \sin(\theta_i - \theta_j) + G_{ii} V_i^2 + \sum_j V_i V_j G_{ij}$$

Key ideas for analysis:

- The case G = 0 is (somewhat) well understood
- (Solvability with G = 0) + $||G/B|| \le \rho$ \implies Solution?

2477

Let
$$A_r$$
 be the (reduced) graph incidence matrix, and define

$$\Gamma := \|A_r^{\mathsf{T}} L_r^{-1} P_r\|_{\infty} \qquad (\text{lossless loading margin})$$
 $\rho := \|\text{diag}(B_{ij})^{-1} A_r^{-1} |A_r| \text{diag}(G_{ij})\|_{\infty} \qquad (r/x \text{ ratio})$
If $\Gamma^2 + 2\Gamma\rho < 1$, then
O $\exists ! \text{ soln. } \theta^* \text{ satisfying } |\theta_i^* - \theta_j^*| \leq \arcsin(\beta_-) \in [0, \frac{\pi}{2}), \text{ where}$

$$\beta_{\pm} = \frac{\Gamma + \rho}{1 + \rho^2} \pm \frac{\rho}{1 + \rho^2} \sqrt{1 - (\Gamma^2 + 2\Gamma\rho)} \in [0, 1].$$
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Conclusions

Framework for studying Lossless Power Flow:

- Fixed-Point Power Flow
- Approximate solution

A Theory of Solvability for Lossless Power Flow Equations — Part I: Fixed-Point Power Flow

John W. Simpson-Porco, Member, IEEE

- New conditions for power flow solvability:
- Ontractive iteration
- Existence/uniqueness
- 6 Generalizes known results
- What's next?
- Lossless meshed case unresolved
- 2 Lossy radial case unresolved
- **Use Set Use Set Us**

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A Theory of Solvability for Lossless Power Flow Equations — Part II: Existence and Uniqueness

John W. Simpson-Porco, Member, IEEE

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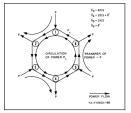
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Questions



https://ece.uwaterloo.ca/~jwsimpso/ jwsimpson@uwaterloo.ca

appendix

Power flow and grid connectivity

"[Power flow feasibility] is one question which is unresolved in power systems analysis, but which is of basic theoretical and practical importance . . . is a given network structurally susceptible to unfeasibility? What type and what value of injections are most likely to result in unfeasible situations?"

– F. D. Galiana, 1975

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